

Exercise Sheet 6

1. Let $x_0 = -1$, $x_1 = 0$ and $x_2 = 2$. Compute the Lagrange basis polynomials associated to these points and use them to interpolate the function

$$f : [-1, 2] \rightarrow \mathbb{R}, \quad \text{with} \quad f(x) = x^4,$$

with a polynomial p of degree 2. Give a bound for the error

$$\max_{x \in [-1, 2]} |f(x) - p(x)|.$$

2. Let $f \in C^1[a, b]$. Consider the polynomial p of the form

$$p(x) = \sum_{j=0}^n K_j(x)f(x_j) + \sum_{j=0}^n M_j(x)f'(x_j),$$

with

$$K_j(x) = [1 - 2(x - x_j)L'_j(x_j)]L_j^2(x), \quad M_j(x) = (x - x_j)L_j^2(x), \quad \text{for } j = 0, \dots, n,$$

where L_j are the Lagrange polynomials, and L'_j their derivatives with respect to x .

Show that

- (a) $p \in \mathbb{P}_{2n+1}$
- (b) $p(x_j) = f(x_j)$, $p'(x_j) = f'(x_j)$, for $j = 0, \dots, n$
- (c) p is unique. *Hint: Assume that there exist another $q \in \mathbb{P}_{2n+1}$ satisfying (b) and derive a contradiction.*

3. Compute the polynomial $p : \mathbb{R} \rightarrow \mathbb{R}$ of Exercise 2 that interpolates the function $f(x) = 1/x$, at the points $x_j = j + 1$, $j = 0, 1, 2$.

4. Show that a linear polynomial of the form

$$p_j(x) = f(x_j) + \frac{f(x_{j+1}) - f(x_j)}{x_{j+1} - x_j}(x - x_j), \quad j = 0, \dots, n$$

satisfies

$$p_j(x) = s(x), \quad \text{for } x \in [x_j, x_{j+1}],$$

where $s \in S^1(\Delta)$ is the linear spline that interpolates f at some partition Δ of the interval $[a, b]$.

5. Let $f(x) = x^2$, $x \in [0, 3]$. Determine the linear spline that interpolates f at the points $x_j = j$, $j = 0, 1, 2, 3$.
6. Consider the function

$$f(x) = \frac{1}{1 + 20x^2}, \quad x \in [-1, 1].$$

Verify Runge's phenomenon in Matlab (or Octave) by implementing polynomials p_n (Lagrange) interpolating f at the equidistant points

$$x_j^{(n)} = -1 + \frac{2j}{n}, \quad j = 0, \dots, n$$

for increasing number n of points. Compare the quality of the approximation for grid points of the form

$$x_j^{(n)} = \cos\left(\frac{\pi}{2} \frac{2j+1}{n+1}\right), \quad j = 0, \dots, n.$$

7. Create a Matlab (or Octave) function that implements linear spline interpolation.
- (i) It takes as input a set of data points $(x_i, y_i) \in \mathbb{R}^2$, $i = 0, \dots, n$, (ii) computes the coefficients of all first degree polynomials and (iii) produces a plot of the spline, which also highlights the data points.